

## **General Description**

The MAX5230/MAX5231 low-power, dual 12-bit voltageoutput digital-to-analog converters (DACs) feature an internal 3ppm/°C precision bandgap voltage reference and precision output amplifiers. The MAX5231 operates on a single 5V supply with an internal 2.5V reference and features a 4.095V full-scale output range. The MAX5230 operates on a single 3V supply with an internal 1.25V reference and features a 2.0475V full-scale output range. The MAX5231 consumes only 470µA while the MAX5230 consumes only 420µA of supply current. Both devices feature low-power (2µA) software- and hardwareenabled shutdown modes.

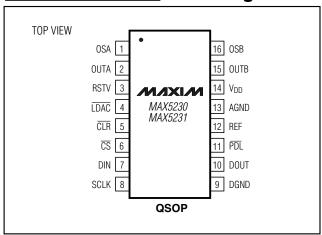
The MAX5230/MAX5231 feature a 13.5MHz SPI™-. QSPITM-, and MICROWIRETM-compatible 3-wire serial interface. An additional data output (DOUT) allows for daisy-chaining and read back. Each DAC has a doublebuffered digital input. The MAX5230/MAX5231 feature two software-selectable shutdown output impedances:  $1k\Omega$  or  $200k\Omega$ . A power-up reset feature sets DAC outputs at ground or at the midscale DAC code.

The MAX5230/MAX5231 are specified over the extended temperature range (-40°C to +85°C) and are available in 16-pin QSOP packages.

## **Applications**

Industrial Process Controls Automatic Test Equipment Digital Offset and Gain Adjustment Motion Control µP-Controlled Systems

# **Pin Configuration**



### Features

- ♦ Internal 3ppm/°C Precision Bandgap Reference 2.465V (MAX5231) 1.234V (MAX5230)
- ♦ 10ppm/°C (max) Full-Scale Output Range 4.095V (MAX5231) 2.0475V (MAX5230)
- **♦ Single-Supply Operation** 5V (MAX5231) 3V (MAX5230)
- **♦ Low Supply Current** 470µA (MAX5231) 420µA (MAX5230)
- **♦ 13.5MHz SPI/QSPI/MICROWIRE-Compatible,** 3-Wire Serial Interface
- ♦ Pin-Programmable Power-Up Reset State to Zero or Midscale Output Voltage
- ♦ Programmable Shutdown Modes with 1kΩ or 200kΩ Internal Output Loads
- ♦ Recalls Output State Prior to Shutdown or Reset
- ♦ Buffered Output Drives 5kΩ || 100pF Loads
- ♦ Space-Saving 16-Pin QSOP Package

# **Ordering Information**

PART	TEMP RANGE	PIN- PACKAGE	INL (LSB)
MAX5230AEEE	-40°C to +85°C	16 QSOP	±0.5
MAX5230BEEE	-40°C to +85°C	16 QSOP	±1
MAX5231AEEE	-40°C to +85°C	16 QSOP	±0.5
MAX5231BEEE	-40°C to +85°C	16 QSOP	±1

### Functional Diagram appears at end of data sheet.

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### **ABSOLUTE MAXIMUM RATINGS**

V <sub>DD</sub> to AGND, DGND	0.3V to +6V	Maximum Current into Any Pin50mA
AGND to DGND	0.3V to +0.3V	Continuous Power Dissipation (T <sub>A</sub> = +70°C)
Digital Inputs to DGND	0.3V to +6V	16-Pin QSOP (derate 8.3mW/°C above +70°C)667mW
Digital Output (DOUT) to DGND	$0.3V \text{ to } V_{DD} + 0.3V$	Operating Temperature Range40°C to +85°C
OUT_ to AGND	$0.3V \text{ to } V_{DD} + 0.3V$	Storage Temperature Range65°C to +150°C
OS_ to AGND	4V to V <sub>DD</sub> + 0.3V	Lead Temperature (soldering, 10s)+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

#### **ELECTRICAL CHARACTERISTICS—MAX5231**

 $(V_{DD} = +4.5V \text{ to } +5.5V, OS\_ = AGND = DGND = 0, R_L = 5k\Omega, C_L = 100pF, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted.}$  Typical values are at  $T_A = +25^{\circ}C.)$ 

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
STATIC PERFORMANCE						
Resolution	N		12			Bits
Interval Newline evity (Nets. 1)	INL	MAX5231A			±0.5	LSB
Integral Nonlinearity (Note 1)	IINL	MAX5231B			±1	LSB
Differential Nonlinearity	DNL				±1	LSB
Offset Error (Note 2)	Vos				±3	mV
Offset-Temperature Coefficient (Note 3)	TCV <sub>OS</sub>			8		μV/°C
Full-Scale Voltage	V <sub>FS</sub>	Code = FFF hex, T <sub>A</sub> = +25°C	4.070	4.095	4.120	V
Full-Scale Temperature Coefficient	TCVFS	MAX5231A		3	10	nnm/°C
(Note 3)	TOVES	MAX5231B (Note 6)		10	30	ppm/°C
Power-Supply Rejection	PSR	4.5V ≤ V <sub>DD</sub> ≤ 5.5V		30	200	μV
DC Crosstalk (Note 4)					100	μV
REFERENCE						
Output Voltage	V <sub>REF</sub>			2.465		V
Output-Voltage Temperature	TCV <sub>REF</sub>	MAX5231A		3		ppm/°C
Coefficient (Note 3)	TOVREF	MAX5231B		10		ррпі/ С
Reference External Load Regulation	Vout/Iout	0 ≤ I <sub>OUT</sub> ≤ 100μA (sourcing)		0.1	2	μV/μΑ
Reference Short-Circuit Current				4		mA
DIGITAL INPUTS						
Input High Voltage	VIH		$0.7 \times V_{DD}$			V
Input Low Voltage	VIL				$0.3 \times V_{DD}$	V
Input Hysteresis	V <sub>H</sub> YS			200		mV
Input Leakage Current	I <sub>IN</sub>	Digital inputs = 0 or V <sub>DD</sub>			±1	μΑ
Input Capacitance	CIN			8		рF
DIGITAL OUTPUTS						
Output High Voltage	VoH	ISOURCE = 2mA	4.25			V
Output Low Voltage	V <sub>OL</sub>	I <sub>SINK</sub> = 2mA			0.2	V
DYNAMIC PERFORMANCE						
Voltage-Output Slew Rate	SR			0.6		V/µs

### **ELECTRICAL CHARACTERISTICS—MAX5231 (continued)**

 $(V_{DD} = +4.5V \text{ to } +5.5V, OS\_ = AGND = DGND = 0, R_L = 5k\Omega, C_L = 100pF, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted.}$  Typical values are at  $T_A = +25^{\circ}C.)$ 

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Voltage-Output Settling Time		To ±0.5LSB, V <sub>STEP</sub> = ±4V (V <sub>DD</sub> - 0.25V) ≥ V <sub>OUT</sub> ≥ 0.25V		10		μs
Output-Voltage Swing (Note 5)				0 to V <sub>DD</sub>		V
OS_ Input Resistance	Ros		83	121		kΩ
Time Required for Output to Settle After Turning on V <sub>DD</sub> (Note 6)				95	400	μs
Time Required for Output to Settle After Exiting Full Power-Down (Note 6)				95	400	μs
Time Required for Output to Settle After Exiting DAC Power-Down (Note 6)				12	160	μs
Digital Feedthrough		$\overline{\text{CS}} = \text{V}_{\text{DD}}, \text{f}_{\text{SCLK}} = 100\text{kHz},$ $\text{V}_{\text{SCLK}} = 5\text{V}_{\text{P-P}}$		5		nV-s
Major-Carry Glitch Energy				90		nV-s
POWER SUPPLIES						
Power-Supply Voltage	$V_{DD}$		4.5		5.5	V
Power-Supply Current (Note 7)	I <sub>DD</sub>			470	525	μΑ
		Full power-down mode		1.4	5	
Power-Supply Current in Power-Down and Shutdown Modes (Note 7)		One DAC shutdown mode		350	390	μΑ
and originown wodes (Note 1)		Both DACs shutdown mode		235	260	

### **ELECTRICAL CHARACTERISTICS—MAX5230**

 $(V_{DD} = +2.7V \text{ to } +3.6V, OS\_ = AGND = DGND = 0, R_L = 5k\Omega, C_L = 100pF, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted.}$  Typical values are at  $T_A = +25^{\circ}C.)$ 

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Resolution	N		12			Bits
Integral Manlingarity (Mate 1)	INL	MAX5230A			±0.5	LSB
Integral Nonlinearity (Note 1)	IINL	MAX5230B			±1	LSB
Differential Nonlinearity	DNL				±1	LSB
Offset Error (Note 2)	Vos				±3	mV
Offset-Temperature Coefficient (Note 3)	TCV <sub>OS</sub>			8		μV/°C
Full-Scale Voltage	VFS	Code = FFF hex, $T_A = +25^{\circ}C$	2.0350	2.0475	2.0600	V
Full-Scale Temperature Coefficient	TCV/=0	MAX5230A		3	10	nnm/0C
(Note 3)	TCVFS	MAX5230B (Note 6)		10	30	ppm/°C
Power-Supply Rejection	PSR	$2.7V \le V_{DD} \le 3.6V$		40	280	μV
DC Crosstalk (Note 4)					100	μV
REFERENCE						
Output Voltage	V <sub>REF</sub>			1.234		V
Output-Voltage Temperature	TCV-==	MAX5230A		3		nnm/0C
Coefficient (Note 3)	TCV <sub>REF</sub>	MAX5230B		10		ppm/°C

### **ELECTRICAL CHARACTERISTICS—MAX5230 (continued)**

 $(V_{DD} = +2.7V \text{ to } +3.6V, OS\_ = AGND = DGND = 0, R_L = 5k\Omega, C_L = 100pF, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted.}$  Typical values are at  $T_A = +25^{\circ}C.)$ 

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Reference External Load Regulation	V <sub>OUT</sub> /I <sub>OUT</sub>	0 ≤ I <sub>OUT</sub> ≤ 100μA (sourcing)		0.1	2	μV/μΑ
Reference Short-Circuit Current				4		mA
DIGITAL INPUTS			•			
Input High Voltage	VIH		0.7 x V <sub>DD</sub>			V
Input Low Voltage	V <sub>IL</sub>				0.3 x V <sub>DD</sub>	V
Input Hysteresis	V <sub>HYS</sub>			200		mV
Input Leakage Current	I <sub>IN</sub>	Digital inputs = 0 or V <sub>DD</sub>			±1	μΑ
Input Capacitance	CIN			8		рF
DIGITAL OUTPUTS						
Output High Voltage	VoH	ISOURCE = 2mA	2.3			V
Output Low Voltage	V <sub>OL</sub>	ISINK = 2mA			0.25	V
DYNAMIC PERFORMANCE						
Voltage-Output Slew Rate	SR			0.6		V/µs
Voltage-Output Settling Time		To $\pm 0.5$ LSB, $V_{STEP} = \pm 2V$ $(V_{DD} - 0.25V) \ge V_{OUT} \ge 0.25V$		10		μs
Output-Voltage Swing (Note 5)				0 to V <sub>DD</sub>		V
OS_ Input Resistance	Ros		83	121		kΩ
Time Required for Output to Settle After Turning on V <sub>DD</sub> (Note 6)				95	400	μs
Time Required for Output to Settle After Exiting Full Power-Down (Note 6)				95	400	μs
Time Required for Output to Settle After Exiting DAC Power-Down (Note 6)				12	160	μs
Digital Feedthrough		CS = VDD, fSCLK = 100kHz, VSCLK = 3VP-P		5		nV-s
Major-Carry Glitch Energy				90		nV-s

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## **ELECTRICAL CHARACTERISTICS—MAX5230 (continued)**

 $(V_{DD} = +2.7V \text{ to } +3.6V, OS\_ = AGND = DGND = 0, R_L = 5k\Omega, C_L = 100pF, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted.}$  Typical values are at  $T_A = +25^{\circ}C.)$ 

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
POWER SUPPLIES						
Power-Supply Voltage	$V_{DD}$		2.7		3.6	V
Power-Supply Current (Note 7)	I <sub>DD</sub>			420	475	μΑ
		Full power-down mode		0.9	5	
Power-Supply Current in Power-Down and Shutdown Modes (Note 7)		One DAC shutdown mode		320	360	μΑ
and Shuldown Modes (Note 1)		Both DACs shutdown mode		220	245	

**Note 1:** Accuracy is guaranteed as shown in the following table:

$V_{\mathrm{DD}}$	ACCURACY GUARANTEED					
(V)	FROM CODE	TO CODE				
3	20	4095				
5	10	4095				

- Note 2: Offset is measured at the code closest to 10mV.
- **Note 3:** Temperature coefficient is determined by the box method in which the maximum  $\Delta V_{OUT}$  over the temperature range is divided by  $\Delta T$ .
- Note 4: DC crosstalk is measured as follows: set DAC A to midscale, and DAC B to zero, and measure DAC A output; then change DAC B to full scale, and measure ΔV<sub>OUT</sub> for DAC A. Repeat the same measurement with DAC A and DAC B interchanged. DC crosstalk is the maximum ΔV<sub>OUT</sub> measured.
- **Note 5:** Accuracy is better than 1LSB for  $V_{OUT} = 10 \text{mV}$  to  $V_{DD}$  180 mV.
- Note 6: Guaranteed by design, not production tested.
- **Note 7:**  $R_{LOAD} = \infty$  and digital inputs are at either  $V_{DD}$  or DGND.

### **TIMING CHARACTERISTICS—MAX5231**

 $(V_{DD} = +4.5V \text{ to } +5.5V, \text{ AGND} = \text{DGND} = 0, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted. Typical values are at } T_A = +25^{\circ}\text{C.})$  (Figures 1 and 2)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
SCLK Clock Period	tcp		74			ns
SCLK Pulse Width High	tсн		30			ns
SCLK Pulse Width Low	tcL		30			ns
CS Fall to SCLK Rise Setup Time	tcss		30			ns
SCLK Rise to CS Rise Hold Time	tCSH		0			ns
DIN Setup Time	t <sub>DS</sub>		30			ns
DIN Hold Time	tDH		0			ns
SCLK Rise to DOUT Valid Propagation Delay Time	t <sub>DO1</sub>	C <sub>LOAD</sub> = 200pF			80	ns
SCLK Fall to DOUT Valid Propagation Delay Time	t <sub>DO2</sub>	C <sub>LOAD</sub> = 200pF			80	ns
SCLK Rise to CS Fall Delay	tcso		10			ns
CS Rise to SCLK Rise Hold Time	tcs1		30			ns
CS Pulse Width High	tcsw		75			ns
LDAC Pulse Width Low	t <sub>LDL</sub>		30			ns
CS Rise to LDAC Rise Hold Time	tcsld	(Note 8)	40			ns

### TIMING CHARACTERISTICS—MAX5230

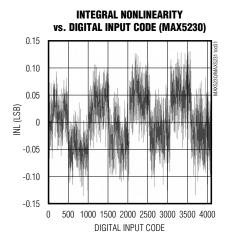
 $(V_{DD} = +2.7V \text{ to } +3.6V, \text{ AGND} = \text{DGND} = 0, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted. Typical values are at } T_A = +25^{\circ}\text{C.})$  (Figures 1 and 2)

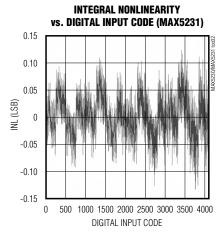
PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
SCLK Clock Period	tcp		74			ns
SCLK Pulse Width High	tсн		30			ns
SCLK Pulse Width Low	t <sub>CL</sub>		30			ns
CS Fall to SCLK Rise Setup Time	tcss		30			ns
SCLK Rise to CS Rise Hold Time	tcsh		0			ns
DIN Setup Time	t <sub>DS</sub>		30			ns
DIN Hold Time	tDH		0			ns
SCLK Rise to DOUT Valid Propagation Delay Time	t <sub>DO1</sub>	C <sub>LOAD</sub> = 200pF			200	ns
SCLK Fall to DOUT Valid Propagation Delay Time	t <sub>DO2</sub>	C <sub>LOAD</sub> = 200pF			200	ns
SCLK Rise to CS Fall Delay	t <sub>CS0</sub>		10			ns
CS Rise to SCLK Rise Hold Time	tCS1		30			ns
CS Pulse Width High	tcsw		75			ns
LDAC Pulse Width Low	t <sub>LDL</sub>		30			ns
CS Rise to LDAC Rise Hold Time	tcsld	(Note 8)	75			ns

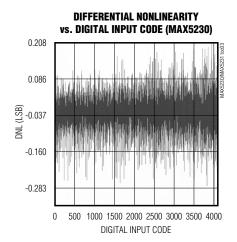
Note 8: This timing requirement applies only to  $\overline{\text{CS}}$  rising edges, which execute commands modifying the DAC input register contents.

# Typical Operating Characteristics

 $(V_{DD} = +3V \text{ (MAX5230)}, V_{DD} = +5V \text{ (MAX5231)}, R_L = 5k\Omega, C_L = 100pF, OS_ = AGND, both DACs enabled with full-scale output code, T_A = +25°C, unless otherwise noted.)$ 

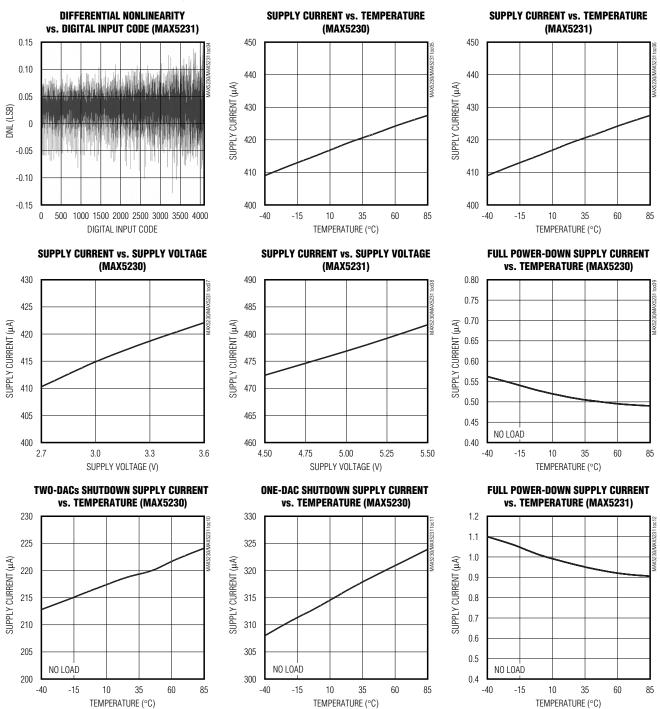






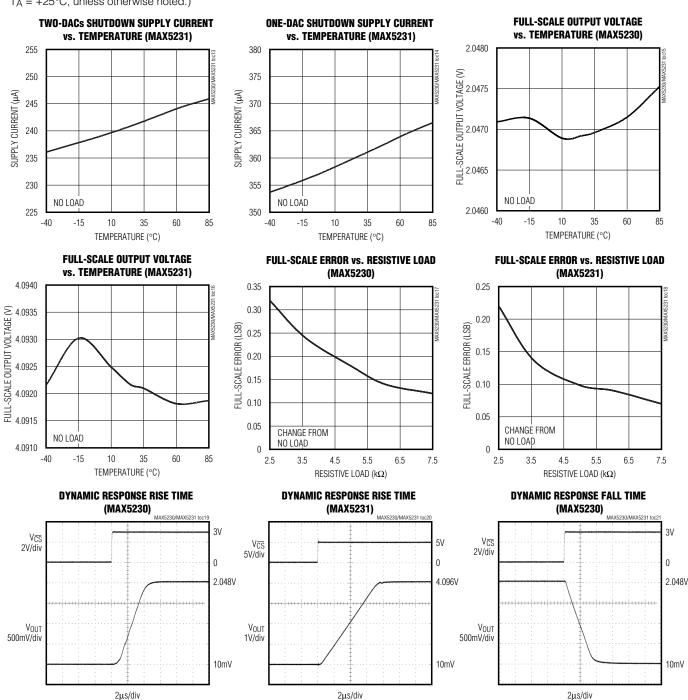
## Typical Operating Characteristics (continued)

 $(V_{DD} = +3V \text{ (MAX5230)}, V_{DD} = +5V \text{ (MAX5231)}, R_L = 5k\Omega, C_L = 100pF, OS_ = AGND, both DACs enabled with full-scale output code, T_A = +25°C, unless otherwise noted.)$ 



## Typical Operating Characteristics (continued)

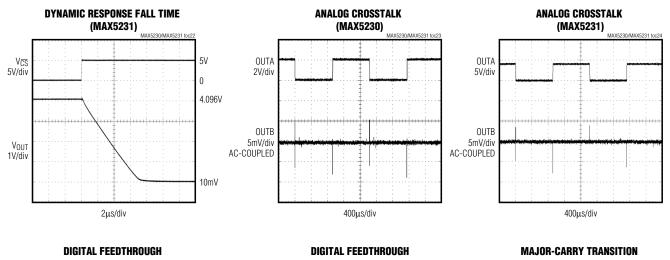
 $(V_{DD} = +3V \text{ (MAX5230)}, V_{DD} = +5V \text{ (MAX5231)}, R_L = 5k\Omega, C_L = 100pF, OS_ = AGND, both DACs enabled with full-scale output code,$  $T_A = +25^{\circ}C$ , unless otherwise noted.)

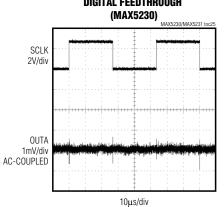


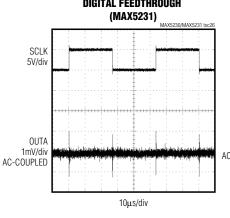
2μs/div

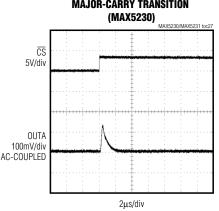
# Typical Operating Characteristics (continued)

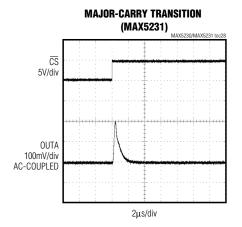
 $(V_{DD} = +3V \text{ (MAX5230)}, V_{DD} = +5V \text{ (MAX5231)}, R_L = 5k\Omega, C_L = 100pF, OS_ = AGND, both DACs enabled with full-scale output code, T_A = +25°C, unless otherwise noted.)$ 

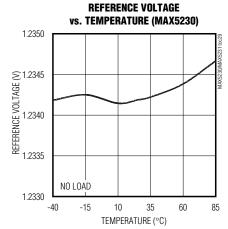


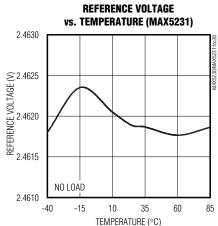












## **Pin Description**

PIN	NAME	FUNCTION
1	OSA	DAC A Offset Adjust
2	OUTA	DAC A Output
3	RSTV	Reset Value Input  1: Connect to V <sub>DD</sub> to select midscale as the reset value.  0: Connect to DGND to select zero as the reset value.
4	LDAC	Load DACs A and B
5	CLR	Clear Input. Both DAC outputs go to zero or midscale. Clears both DAC internal registers (input register and DAC register) to its predetermined (RSTV) state.
6	CS	Chip-Select Input
7	DIN	Serial Data Input. Data is clocked in on the rising edge of SCLK.
8	SCLK	Serial Clock Input
9	DGND	Digital Ground
10	DOUT	Serial Data Output
11	PDL	Power-Down Lockout. Disables shutdown of both DACs when low.
12	REF	Reference Output. Reference provides a 2.465V (MAX5231) or 1.234V (MAX5230) nominal output.
13	AGND	Analog Ground
14	V <sub>DD</sub>	Positive Power Supply. Bypass $V_{DD}$ with a 0.1 $\mu$ F capacitor in parallel with a 4.7 $\mu$ F capacitor to AGND, and bypass $V_{DD}$ with a 0.1 $\mu$ F capacitor to DGND.
15	OUTB	DAC B Output
16	OSB	DAC B Offset Adjust

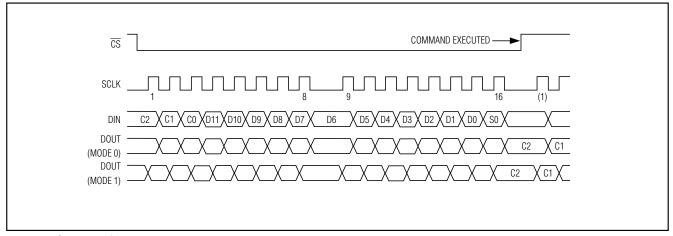


Figure 1. Serial Interface Timing

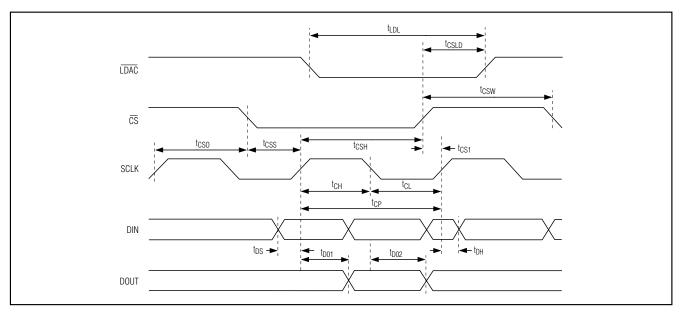


Figure 2. Detailed Serial Interface Timing

## **Detailed Description**

The MAX5230/MAX5231 12-bit, voltage-output DACs are easily configured with a 3-wire SPI-, QSPI-, MICROWIRE-compatible serial interface. The devices include a 16-bit data-in/data-out shift register and have an input consisting of an input register and a DAC register. In addition, these devices employ precision trimmed internal resistors to produce a gain of 1.6384V/V, maximizing the output voltage swing, and a programmable-shutdown output impedance of 1k $\Omega$  or 200k $\Omega$  The full-scale output voltage is 4.095V for the MAX5231 and 2.0475V for the MAX5230. These devices produce a weighted output voltage proportional to the digital input code with an inverted Rail-to-Rail ladder network (Figure 3).

### **Internal Reference**

The MAX5230/MAX5231 use an on-board precision bandgap reference to generate an output voltage of 1.234V (MAX5230) or 2.465V (MAX5231). With a low temperature coefficient of only 3ppm/°C, REF can source up to 100µA and is stable for capacitive loads less than 35pF.

#### **Output Amplifiers**

The output amplifiers have internal resistors that provide for a gain of 1.6384V/V when OS\_ is connected to AGND. The output amplifiers have a typical slew rate of

Rail-to-Rail is a registered trademark of Nippon Motorola, Ltd.

 $0.6V/\mu s$  and settle to 1/2LSB within  $10\mu s$  with a load of  $5k\Omega$  in parallel with 100pF. Use the serial interface to set the shutdown output impedance of the amplifiers to  $1k\Omega$  or  $200k\Omega$ .

OS\_ can be used to produce an offset voltage at the output. For instance, to achieve a 1V offset, apply -1V to OS\_ to produce an output range from 1V to (1V + VFS/VREF). Note that the DAC's output range is still limited by the maximum output voltage specification.

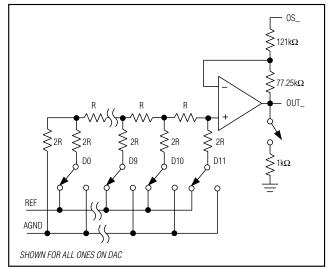


Figure 3. Simplified DAC Circuit Diagram

**Table 1. Serial Data Format** 

MSB <> LSB					
3 Control Bits	MSB 12 Data Bits LSB	Sub-Bit			
C2C0	D11D0	S0			

#### **Serial Interface**

The 3-wire serial interface (SPI, QSPI, MICROWIRE compatible) used in the MAX5230/MAX5231 allows for complete control of DAC operations (Figures 4 and 5). Figures 1 and 2 show the timing for the serial interface. The serial word consists of 3 control bits followed by 12 data bits (MSB first) and 1 sub-bit as described in Tables 1, 2, and 3. When the 3 control bits are all zero or all 1, D11–D8 are used as additional control bits, allowing for greater DAC functionality.

The digital inputs allow any of the following: loading the input register(s) without updating the DAC register(s), updating the DAC register(s) from the input register(s), or updating the input and DAC register(s) simultane-

ously. The control bits and D11-D8 allow the DACs to operate independently.

Send the 16-bit data as one 16-bit word (QSPI) or two 8-bit packets (SPI, MICROWIRE), with  $\overline{CS}$  low during this period. The control bits and D11-D8 determine which registers update and the state of the registers when exiting shutdown. The 3-bit control and D11-D8 determine the following:

- · Registers to be updated
- Selection of the power-down and shutdown modes

The general timing diagram of Figure 1 illustrates data acquisition. Driving  $\overline{CS}$  low enables the device to receive data. Otherwise the interface control circuitry is disabled. With  $\overline{CS}$  low, data at DIN is clocked into the register on the rising edge of SCLK. As  $\overline{CS}$  goes high, data is latched into the input and/or DAC registers, depending on the control bits and D11–D8. The maximum clock frequency guaranteed for proper operation is 13.5MHz. Figure 2 depicts a more detailed timing diagram of the serial interface.

**Table 2. Serial-Interface Programming Commands** 

	16-BIT SERIAL WORD				FUNCTION		
C2	C1	C0	D11D0	S0*	FUNCTION		
0	0	1	12-bit DAC data	0	Load input register A; DAC registers are unchanged.		
0	1	0	12-bit DAC data	0	Load input register A; all DAC registers are updated.		
0	1	1	12-bit DAC data	0	Load all DAC registers from the shift register (start up both DACs with new data, and load the input registers).		
1	0	0	xxxxxxxxxx	0	Update both DAC registers from their respective input registers (star up both DACs with data previously stored in the input registers).		
1	0	1	12-bit DAC data	0	Load input register B; DAC registers are unchanged.		
1	1	0	12-bit DAC data	0	Load input register B; all DAC registers are updated.		
1	1	1	P1A P1B X X X X X X X X X X	0	Shut down both DACs, respectively, according to bits P1A and P1B (see Table 3). Internal bias and reference remain active.		
0	0	0	001XXXXXXXX	0	Update DAC register A from input register A (start up DAC A with data previously stored in input register A).		
0	0	0	0 1 1 P1A P1B X X X X X X X	0	Full Power-Down. Power down the main bias generator and shut down both DACs, respectively, according to bits P1A and P1B (see Table 3).		
0	0	0	101XXXXXXXX	0	Update DAC register B from input register B (start up DAC B with data previously stored in input register B).		
0	0	0	1 1 0 P1A X X X X X X X X	0	Shut down DAC A according to bit P1A (see Table 3).		
0	0	0	1 1 1 P1B X X X X X X X X	0	Shut down DAC B according to bit P1B (see Table 3).		
0	0	0	1000XXXXXXX	0	Mode 0. DOUT clocked out on SCLK falling edge (default).		
0	0	0	1001XXXXXXXX	0	Mode 1. DOUT clocked out on SCLK rising edge.		

X = Don't care.

<sup>\*</sup> S0 must be zero for proper operation.

### **Power-Down and Shutdown Modes**

As described in Tables 2 and 3, several serial interface commands put one or both of the DACs into shutdown mode. Shutdown modes are completely independent for each DAC. In shutdown, the amplifier output becomes high impedance, and OUT\_ terminates to OS\_ through the 200k $\Omega$  (typ) gain resistors. Optionally (see Tables 2 and 3), OUT\_ can have an additional termination of 1k $\Omega$  to AGND.

Full power-down mode shuts down the main bias generator, reference, and both DACs. The shutdown impedance of the DAC outputs can still be controlled independently, as described in Tables 2 and 3.

A serial interface command exits shutdown mode and updates a DAC register. Each DAC can exit shutdown at the same time or independently (see Tables 2 and 3). For example, if both DACs are shut down, updating the DAC A register causes DAC A to power up, while DAC B remains shut down. In full power-down mode, powering up either DAC also powers up the main bias generator and reference. To change from full power-down to both DACs shutdown requires the waking of at least one DAC between states.

When powering up the MAX5230/MAX5231 (powering  $V_{DD}$ ), allow 400 $\mu$ s (max) for the output to stabilize. When exiting full power-down mode, also allow 400 $\mu$ s (max) for the output to stabilize. When exiting DAC shutdown mode, allow 160 $\mu$ s (max) for the output to stabilize.

# Reset Value (RSTV) and Clear (CLR) Inputs

Driving  $\overline{\text{CLR}}$  low asynchronously forces both DAC outputs and all the internal registers (input registers and DAC registers) for both DACs to either zero or midscale, depending on the level at RSTV. RSTV = DGND sets the zero value, and RSTV, = VDD sets the midscale value.

The internal power-on reset circuit sets the DAC outputs and internal registers to either zero or midscale when power is first applied to the device, depending on the level at RSTV as described in the preceding paragraph. The DAC outputs are enabled after power is first applied. In order to obtain the midscale value on power-up (RSTV =  $V_{DD}$ ), the voltage on RSTV must rise simultaneously with the  $V_{DD}$  supply.

#### Table 3. P1 Shutdown Modes

P1 (A/B)	SHUTDOWN MODE		
0	Shut down with internal $1k\Omega$ load to GND		
1	Shut down with internal 200kΩ load to GND		

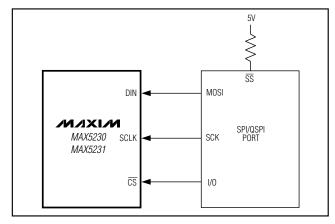


Figure 4. SPI/QSPI Interface Connections

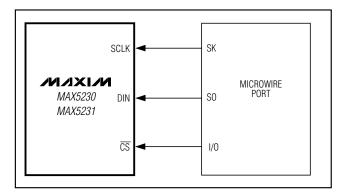


Figure 5. Connections for MICROWIRE

### Load DAC Input (LDAC)

Asserting LDAC asynchronously loads the DAC registers from their corresponding input registers (DACs that are shut down remain shut down). The LDAC input is totally asynchronous and does not require any activity on CS, SCLK, or DIN in order to take effect. If LDAC is asserted coincident with a rising edge of CS, which executes a serial command modifying the value of either DAC input register, then LDAC must remain asserted for at least 30ns following the CS rising edge. This requirement applies only for serial commands that modify the value of the DAC input registers.

#### Power-Down Lockout Input (PDL)

Driving PDL low disables shutdown of either DAC. When PDL is low, serial commands to shut down either DAC are ignored. When either DAC is in shutdown mode, a high-to-low transition on PDL brings the DACs and the reference out of shutdown with DAC outputs set to the state prior to shutdown.

## **Applications Information**

### **Definitions**

#### Integral Nonlinearity (INL)

Integral nonlinearity (Figure 6a) is the deviation of the values on an actual transfer function from a straight line. This straight line can be either a best-straight-line fit (closest approximation to the actual transfer curve) or a line drawn between the endpoints of the transfer function, once offset and gain errors have been nullified. For a DAC, the deviations are measured at every single step.

#### Differential Nonlinearity (DNL)

Differential nonlinearity (Figure 6b) is the difference between an actual step height and the ideal value of 1LSB. If the magnitude of the DNL is less than 1LSB, the DAC guarantees no missing codes and is monotonic.

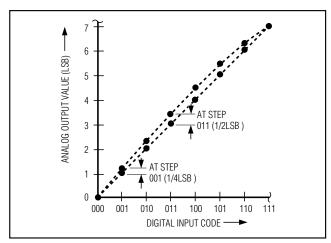


Figure 6a. Integral Nonlinearity

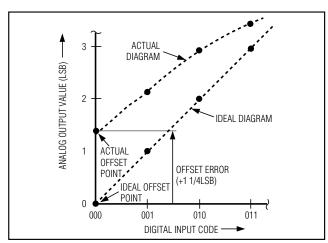


Figure 6c. Offset Error

### Offset Error

The offset error (Figure 6c) is the difference between the ideal and the actual offset point. For a DAC, the offset point is the step value when the digital input is zero. This error affects all codes by the same amount and can usually be compensated for by trimming.

#### Gain Error

Gain error (Figure 6d) is the difference between the ideal and the actual full-scale output voltage on the transfer curve, after nullifying the offset error. This error alters the slope of the transfer function and corresponds to the same percentage error in each step.

### Settling Time

The settling time is the amount of time required from the start of a transition, until the DAC output settles to its new output value within the converter's specified accuracy.

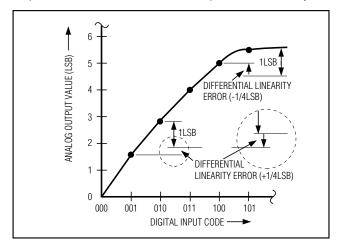


Figure 6b. Differential Nonlinearity

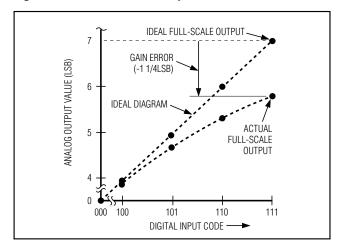


Figure 6d. Gain Error

**Table 4. Unipolar Code Table** 

DAC CON	ITENTS	ANALOG OUTPUT (V)		
MSB	LSB	MAX5230	MAX5231	
1111 1111 1	111 (0)	2.04750	4.0950	
1000 0000 0	001 (0)	1.02425	2.0485	
1000 0000 0	000 (0)	1.02375	2.0475	
0111 1111 1	111 (0)	1.02325	2.0465	
0000 0000	001 (0)	0.00050	0.0010	
0000 0000 0	000 (0)	0	0	

### Digital Feedthrough

Digital feedthrough is noise generated on the DAC's output when any digital input transitions. Proper board layout and grounding significantly reduce this noise, but there is always some feedthrough caused by the DAC itself.

### **Unipolar Output**

Figure 7 shows the MAX5230/MAX5231 configured for unipolar, rail-to-rail operation. The MAX5231 produces a 0 to 4.095V output, while the MAX5230 produces 0 to 2.0475V output. Table 4 lists the unipolar output codes.

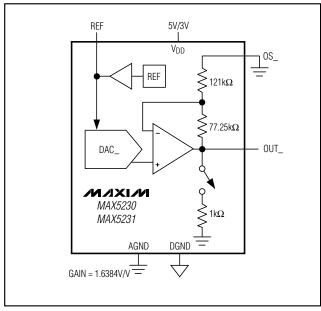


Figure 7. Unipolar Output Circuit (Rail-to-Rail)

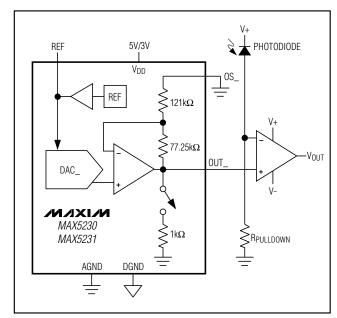


Figure 8. Digital Calibration

# Digital Calibration and Threshold Selection

Figure 8 shows the MAX5230/MAX5231 in a digital calibration application. With a bright light value applied to the photodiode (on), the DAC is digitally ramped until it trips the comparator. The microprocessor ( $\mu P$ ) stores this "high" calibration value. Repeat the process with a dim light (off) to obtain the dark current calibration. The  $\mu P$  then programs the DAC to set an output voltage at the midpoint of the two calibrated values. Applications include tachometers, motion sensing, automatic readers, and liquid clarity analysis.

#### Sharing a Common DIN Line

Several MAX5230/MAX5231s may share one common DIN signal line (Figure 9). In this configuration, the data bus is common to all devices; data is not shifted through a daisy-chain. The SCLK and DIN lines are shared by all devices, but each IC needs its own dedicated  $\overline{\text{CS}}$  line.

### **Daisy-Chaining Devices**

Any number of MAX5230/MAX5231s can be daisy-chained by connecting the serial data output (DOUT) of one device to the digital input (DIN) of the following device in the chain (Figure 10).

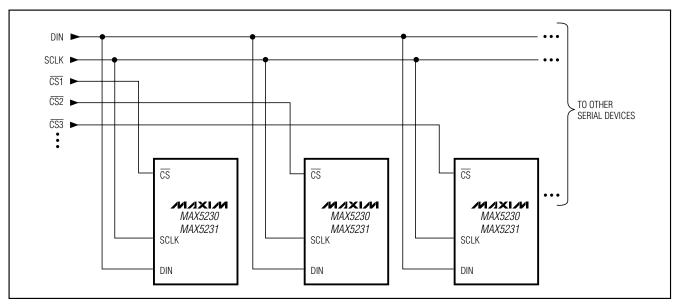


Figure 9. Multiple MAX5230/MAX5231s Sharing a Common DIN Line

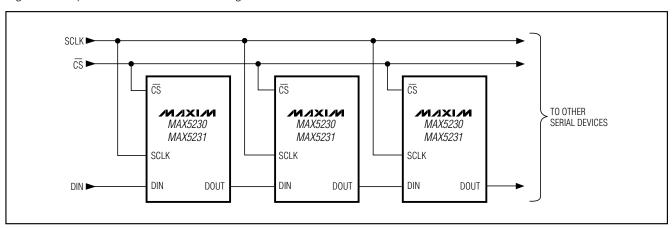


Figure 10. Daisy-Chaining MAX5230/MAX5231 Devices

# Power-Supply and Bypassing Considerations

On power-up, the input and DAC registers are cleared to either zero (RSTV = DGND) or midscale (RSTV =  $V_{DD}$ ). Bypass  $V_{DD}$  with a 4.7 $\mu$ F capacitor in parallel with a 0.1 $\mu$ F capacitor to AGND, and bypass  $V_{DD}$  with a 0.1 $\mu$ F capacitor to DGND. Minimize lead lengths to reduce lead inductance.

#### Grounding and Layout Considerations

Digital and AC transient signals on AGND or DGND can create noise at the output. Connect AGND and DGND to the highest quality ground available. Use proper

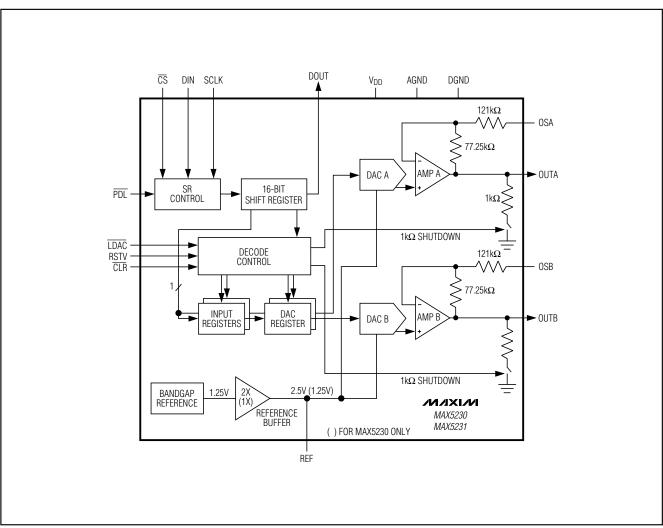
grounding techniques, such as a multilayer board with a low-inductance ground plane or star connect all ground return paths back to the MAX5230/MAX5231 AGND. Carefully lay out the traces between channels to reduce AC cross-coupling and crosstalk. Wire-wrapped boards and sockets are not recommended. If noise becomes an issue, shielding may be required.

Chip Information

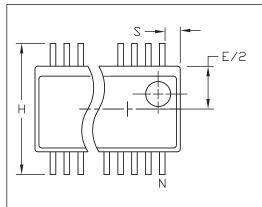
TRANSISTOR COUNT: 4745

PROCESS: BICMOS

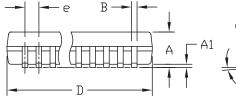
## Functional Diagram

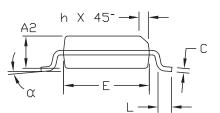


## Package Information



	INCH	ES	MILLIMETERS		
DIM	MIN	MAX	MIN	MAX	
Α	.061	.068	1.55	1.73	
A1	.004	.0098	0.102	0.249	
A2	.055	.061	1.40	1.55	
В	.008	.012	0.20	0.31	
С	.0075	.0098	0.191	0.249	
D	SEE VARIATIONS				
E	.150	.157	3.81	3.99	
е	.025	BSC	0.635 BSC		
Н	.230	.244	5.84	6.20	
h	.010	.016	0.25	0.41	
L	.016 .00		0.41	0.89	
N	SEE VARIATIONS				
α	0°	8*	0*	8*	





#### VARIATIONS:

	INCHE	2	MILLIM			
	MIN.	MAX.	MIN.	MAX.	N	
D	.189	.196	4.80	4.98	16	АΑ
S	.0020	.0070	0.05	0.18		
D	.337	.344	8.56	8.74	20	ΑВ
S	.0500	.0550	1.270	1.397		
D	.337	.344	8.56	8.74	24	AC
S	.0250	.0300	0.635	0.762		
D	.386	.393	9.80	9.98	28	ΑD
S	.0250	.0300	0.635	0.762		

- 1). D & E DO NOT INCLUDE MOLD FLASH OR PROTRUSIONS.
  2). MOLD FLASH OR PROTRUSIONS NOT TO EXCEED .006" PER SIDE.
- 3). CONTROLLING DIMENSIONS: INCHES.
- 4). MEETS JEDEC MO137.



21-0055

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